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**GOAL: Automate wizard dialogue in a GUI to create reliable, tractable training data without sacrificing naturalness**

## Introduction

- Problem: We don't know how people will communicate with robots given no linguistic constraints and what the expectations are for communication in return
- We want to leverage dialogue management approaches from human-virtual human dialogue and apply it to HRI
- We need to balance naturalness with functionality (e.g. leverage human conversational techniques such as those described in *Jurafsky & Martin 2007*)
- Experiment is a two-person Wizard of Oz setup; it is beneficial to have two people performing the task of simulating robot automation (*Marge et al. 2016a*)



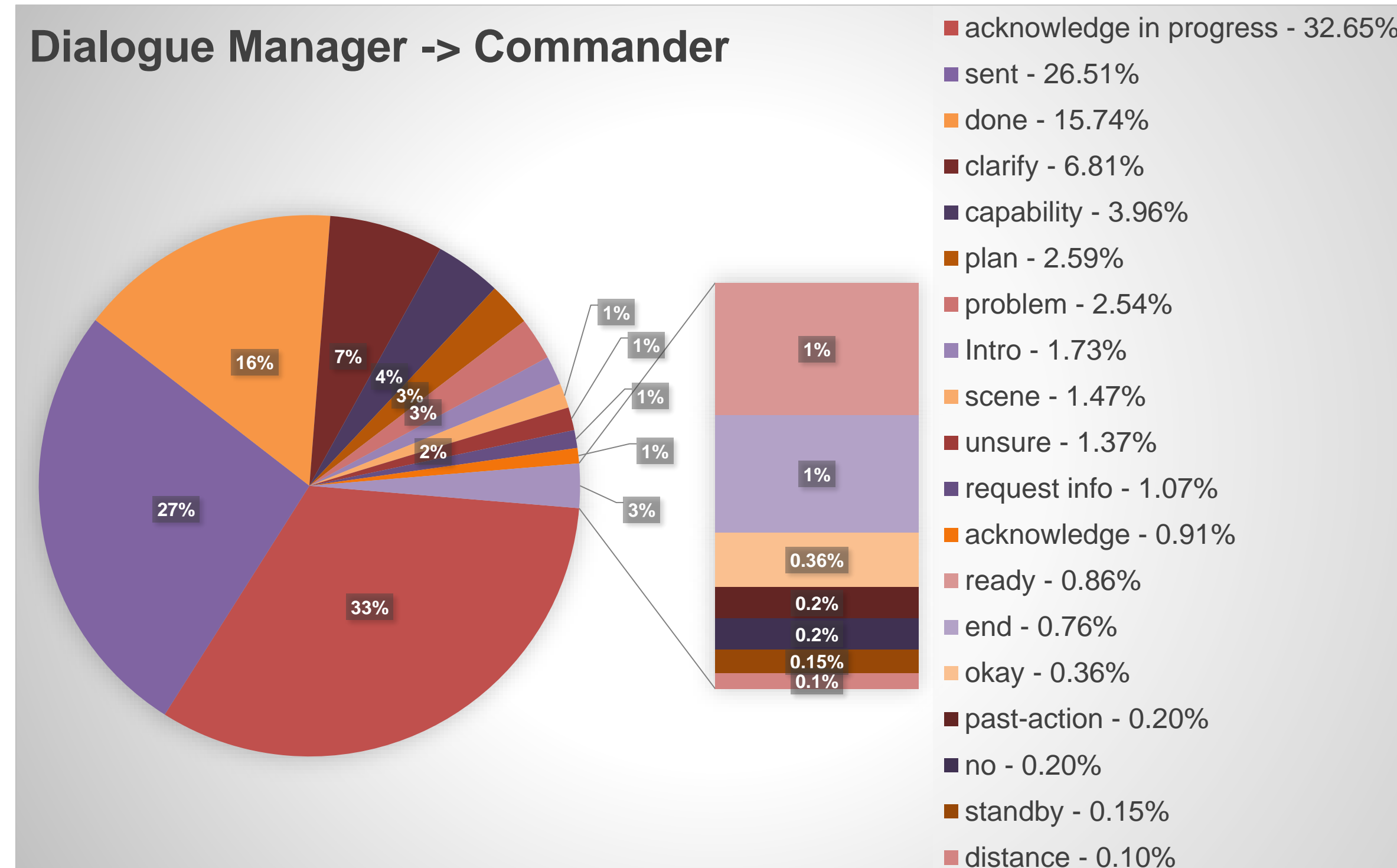
**The Experiment:** Collaborative search and navigation task with a robot teammate, where robot is directed using natural language as opposed to teleoperation

10 participants engaged in three separate 20 minute tasks with a robot (Dialogue Manager Wizard and Robot Navigator, participant never interfaces with RN directly), leading to 30 experiment runs with 2 bidirectional channels of communication

## Analysis

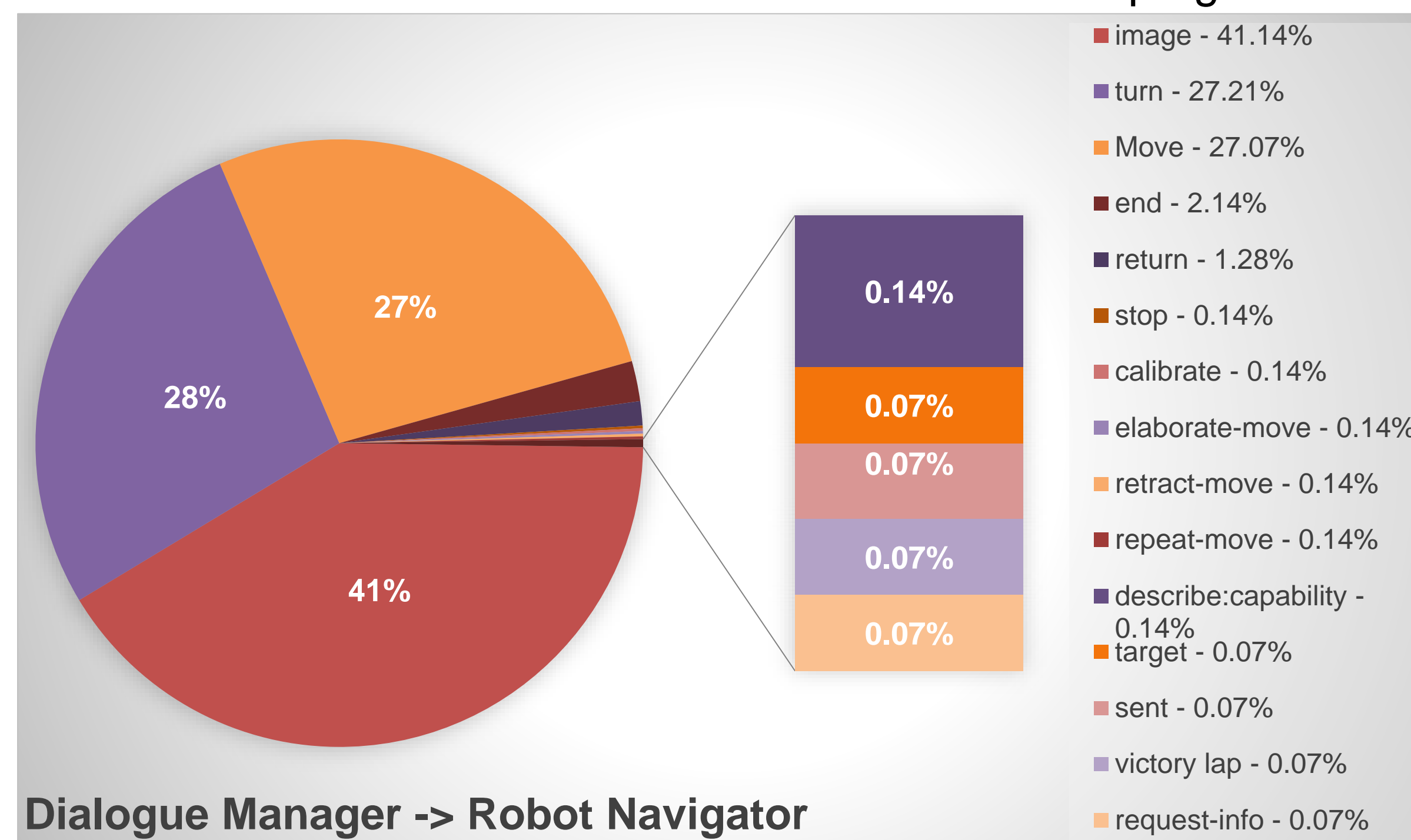
- All 60 exchanges were first annotated according to dialogue moves (*Marge et al. 2016b*)
- Validated and expanded set of dialogue moves as needed
- Frequency analyses were then performed on dialogue move parameters, dialogue move types, and unique utterance occurrences
- In dialogue parameters, only few occurred frequently: left/right, forward, 45 and 90 degrees, etc) – high variability in speech data!
- Non-singleton utterances have full coverage in the current version of the interface (53 unique utterances covers 85.85% of total – 1692/1971 total utterances)

## Data



Task	intro	also_ready	ready	tech issues	standby	hold push-to-talk reminder	task complete	
Feedback	executing	sent	done	calibrating	calibration complete	yes	no	ok
Clarify	unsure of object referred to	unsure object meant	describe w color, size, position?	describe another way?	unsure of doorway	unsure doorway meant	unsure of room	unsure of wall
								which doorway?

Pictured are the analyses performed on counts of communications of the dialogue manager. The counts are of annotations of dialogue moves. These frequency analyses combined with the "wizardsourced" data served as basis for developing the GUI.



Move	move DIR DIST	move DIST	move 1 foot	move 2 feet	move 3 feet	move 5 feet	move 10 feet	move back DIST	move back 1 foot	move TARGET	move close to TARGET
	move PATH	move forward PATH	move back PATH	move TARGET PATH	move GOAL	move forward TARGET	move back TARGET	move thru doorway	move into hallway	move to room center	move DIST to GOAL
	move DIST from SOURCE										
Turn	turn right DEGREES	turn left DEGREES	turn TARGET	face N	face E	face W	face S	turn right 90	turn left 90	turn right 45	turn left 45

## Discussion

- Our experiment methodology differs from Q-A type systems in that it strives to be conversationally interactive with humans and contextually aware of its environment at large
- GUI was created to address our experiment's goal towards movement to automation
- Delicate balance must be considered between technical constraints and conversational techniques
- Synonymous wordings also present their own unique issue - *context dependent*
- To solve this, we use careful consideration when deciding if coverage for an utterance has been achieved in the GUI

## Steps Forward

- Stress testing the GUI using aligned language data
- Analysis of coverage for singleton utterances
- Assess impacts of automated vs human dialogue manager after Experiment 2 (which is intended to assess any impact on dialogue exchanges from the graphical interface vs free response typing).

## References

Dan Jurafsky and James H Martin. 2007. *Speech and language processing*. Pearson Prentice Hall, Upper Saddle River, N.J., edition.

Matthew Marge, Claire Bonial, Brendan Byrne, Taylor Cassidy, A. William Evans, Susan G. Hill and Clare Voss. 2016. Applying the Wizard-of-Oz Technique to Multimodal Human-Robot Dialogue. In Proc. of IEEE RO-MAN, Columbia University, Teachers College.

Matthew Marge, Claire Bonial, Kimberly A. Pollard, Ron Artstein, Brendan Byrne, Susan G. Hill, Clare Voss, and David Traum. 2016. Assessing Agreement in Human-Robot Dialogue Strategies: A Tale of Two Wizards. In Proc. of IVA.

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